

**CRITICALITY OF LAGRANGE MULTIPLIERS IN
CONSTRAINED OPTIMIZATION WITH
APPLICATIONS TO SQP**

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VARIATIONAL SYSTEMS

Consider the variational system (VS)

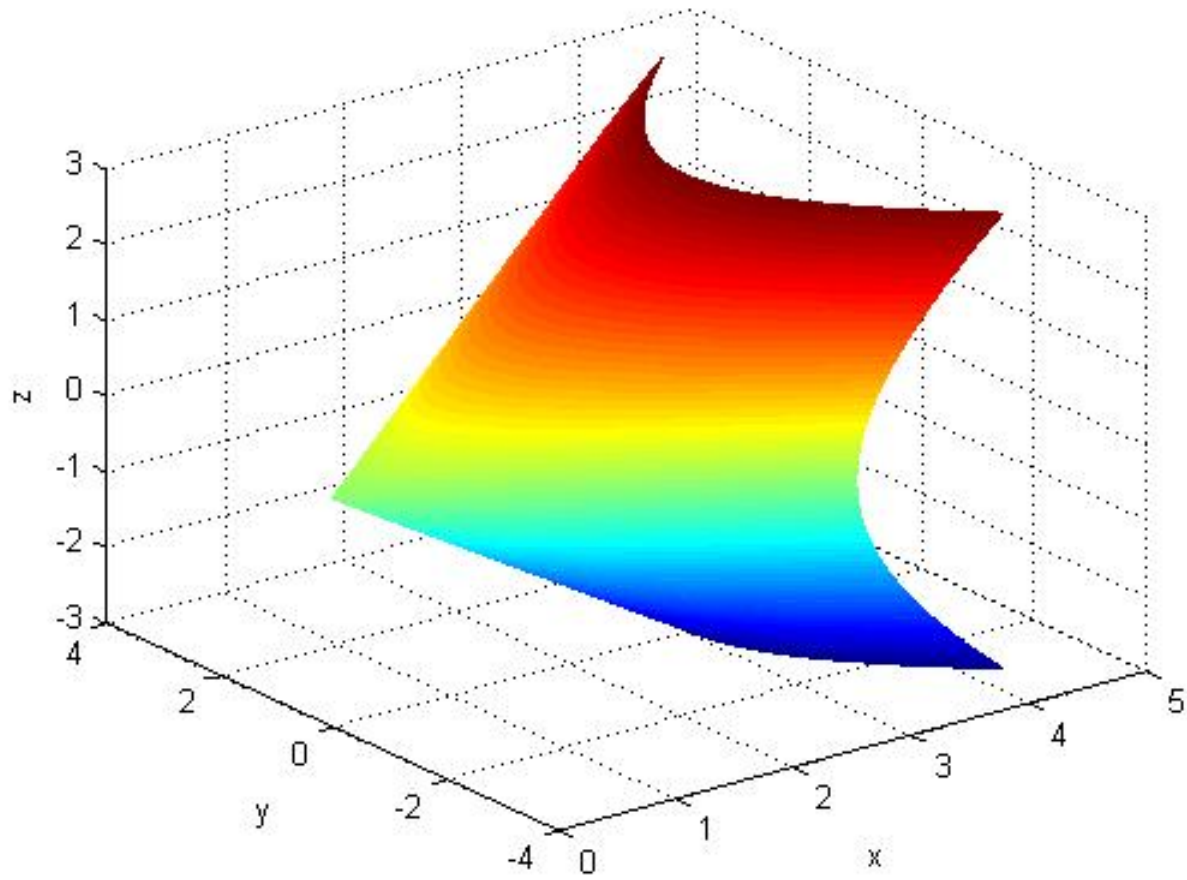
$$\Psi(x, \lambda) := f(x) + \nabla\Phi(x)^*\lambda = 0, \quad \lambda \in N_{\Theta}(\Phi(x))$$

where $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a \mathcal{C}^1 while $\Phi: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a \mathcal{C}^2 mappings, $\Theta \subset \mathbb{R}^m$ is a closed set with N_{Θ} standing for its (limiting) normal cone. A major source for such systems comes from KKT in constrained optimization (CO)

$$\text{minimize } \varphi_0(x) \text{ subject to } \Phi(x) \in \Theta$$

with $f = \nabla\varphi_0$. When Θ is a convex cone, the latter problems are known as conic programs

ICE-CREAM CONE IN 3D



SUBGRADIENT GRAPHICAL DERIVATIVE

The **graphical derivative** of a set-valued mapping $F: \mathbb{R}^n \rightrightarrows \mathbb{R}^p$ at $(\bar{x}, \bar{y}) \in \text{gph } F$ is

$$DF(\bar{x}, \bar{y})(u) = \left\{ v \in \mathbb{R}^p \mid (u, v) \in T\left((\bar{x}, \bar{y}); \text{gph } F\right) \right\}, \quad u \in \mathbb{R}^n$$

where $T(z; \Omega)$ is a **contingent cone** to Ω at z defined by

$$T(z; \Omega) := \left\{ w \in \mathbb{R}^m \mid \exists z_k \xrightarrow{\Omega} z, \alpha_k \geq 0, \alpha_k(z_k - z) \rightarrow w \right\}$$

We use the **2nd-order subgradient graphical derivative** construction $D\partial\theta$ while noting that for $\theta \in \mathcal{C}^2$ we have

$$(D\partial\theta)(\bar{z}, \theta(\bar{z}))(u) = \left\{ \nabla^2\theta(\bar{z})u \right\}, \quad u \in \mathbb{R}^m$$

For various important classes of extended-real-valued functions θ considered below the construction $D\partial\theta$ is explicitly **calculated** entirely via the **given data** of θ

CRITICAL AND NONCRITICAL MULTIPLIERS

Given $\bar{x} \in \mathbb{R}^n$ satisfying the stationary condition

$$0 \in f(\bar{x}) + \partial(\delta_{\Theta} \circ \Phi)(\bar{x})$$

we define the set of Lagrange multipliers associated with \bar{x} by

$$\Lambda(\bar{x}) := \left\{ \lambda \in \mathbb{R}^m \mid \Psi(\bar{x}, \lambda) = 0, \lambda \in N_{\Theta}(\Phi(\bar{x})) \right\}$$

DEFINITION (BM-Sarabi18) The multiplier $\bar{\lambda} \in \Lambda(\bar{x})$ is critical if there is $\xi \neq 0$ satisfying

$$0 \in \nabla_x \Psi(\bar{x}, \bar{\lambda})\xi + \nabla \Phi(\bar{x})^* DN_{\Theta}(\Phi(\bar{x}), \bar{\lambda})(\nabla \Phi(\bar{x})\xi)$$

The Lagrange multiplier $\bar{\lambda} \in \Lambda(\bar{x})$ is noncritical when the above inclusion admits only the trivial solution $\xi = 0$.

ORIGINAL DEFINITION AND DISCUSSION

ORIGINAL DEFINITION (Izmailov05) for $\theta = \delta_{\{0\}^m}$ (i.e. for KKT systems in NLPs with smooth equality constraints): the multiplier $\bar{\lambda}$ is **critical** if the primal-dual system

$$\nabla_x \Psi(\bar{x}, \bar{\lambda})\xi \in \text{rge } \nabla \Phi(\bar{x})^*, \quad \nabla \Phi(\bar{x})\xi = 0$$

admits a nontrivial solution

Izmailov, Solodov, and their collaborators demonstrate that critical multipliers are largely responsible for **slow convergence** of major **primal-dual algorithms** of optimization. This is due to the fact that the set of critical multipliers is an **attractor** for the **dual** sequence of multipliers $\{\lambda_k\}$ in such algorithms and thus slow down the convergence of the **primal** sequence $\{x_k\}$ in numerical methods. Therefore, **critical multipliers should be ruled out** for appropriate classes of stationary/optimal solutions

REDUCIBLE SETS

DEFINITION A closed set $\Theta \subset \mathbb{R}^m$ is \mathcal{C}^2 -cone reducible at $\bar{z} = \Phi(\bar{x}) \in \Theta$ to a closed convex subcone $C \subset \mathbb{R}^p$ if there exist a neighborhood $\mathcal{O} \subset \mathbb{R}^m$ of \bar{z} and a \mathcal{C}^2 -smooth mapping $h: \mathbb{R}^m \rightarrow \mathbb{R}^p$ such that

$$\Theta \cap \mathcal{O} = \{z \in \mathcal{O} \mid h(z) \in C\}, \quad h(\bar{z}) = 0, \quad \nabla h(\bar{z}) \text{ is surjective}$$

In contrast to the classical definition by Bonnans and Shapiro (2000), we do not assume that C is pointed and Θ is convex

EXAMPLES: second-order/Lorentz/ice-cream cone and their products, SDP cone, copositive cone, and other major constraint systems in conic programming.

CRITICAL MULTIPLIERS FOR REDUCIBLE SETS

THEOREM Let \bar{x} be a stationary point, $\bar{\lambda} \in \Lambda(\bar{x})$, Θ be \mathcal{C}^2 -cone reducible at $\bar{z} := \Phi(\bar{x})$ to a closed convex cone C , let

$$K_{\Theta}(\bar{z}, \bar{\lambda}) = T_{\Theta}(\bar{z}) \cap \{\bar{\lambda}\}^{\perp} \quad \text{with } \bar{\lambda} \in N_{\Theta}(\bar{z})$$

be the **critical cone** to Θ at \bar{x} for $\bar{\lambda}$, and let $\bar{\mu}$ be a **unique** solution to the system

$$\bar{\lambda} = \nabla h(\bar{z})^* \bar{\mu}, \quad \bar{\mu} \in N_C(h(\bar{z}))$$

Then $\bar{\lambda}$ is **critical multiplier** if and only if the system

$$\begin{aligned} \nabla_x \Psi(\bar{x}, \bar{\lambda}) \xi + \nabla \Phi(\bar{x})^* \eta &= 0 \\ \eta - \nabla^2 \langle \bar{\mu}, h \rangle(\bar{z}) \nabla \Phi(\bar{x}) \xi &\in N_{K_{\Theta}(\bar{z}, \bar{\lambda})}(\nabla \Phi(\bar{x}) \xi) \end{aligned}$$

admits a solution $(\xi, \eta) \in \mathbb{R}^n \times \mathbb{R}^m$ such that $\xi \neq 0$

CALMNESS PROPERTIES OF MULTIFUNCTIONS

DEFINITION We say that a set-valued mapping $F: \mathbb{R}^n \rightrightarrows \mathbb{R}^m$ is **calm** at $(\bar{x}, \bar{y}) \in \text{gph } F$ if there exist $\ell \geq 0$ and a neighborhood U of \bar{x} such that

$$F(x) \cap V \subset F(\bar{x}) + \ell \|x - \bar{x}\| \mathcal{B} \quad \text{for all } x \in U$$

where \mathcal{B} stands for the closed unit ball. The **isolated calmness** property of F at (\bar{x}, \bar{y}) is defined by

$$F(x) \cap V \subset \{\bar{y}\} + \ell \|x - \bar{x}\| \mathcal{B} \quad \text{for all } x \in U$$

It is well known that the calmness and isolated calmness properties are equivalent to **metric subregularity** and **strong metric subregularity** of the inverse mapping F^{-1} at (\bar{y}, \bar{x}) , respectively

CANONICAL PERTURBATION AND SEMI-ISOLATED CALMNESS

Consider the mapping $G: \mathbb{R}^n \times \mathbb{R}^m \Rightarrow \mathbb{R}^n \times \mathbb{R}^m$ given by

$$G(x, \lambda) := \begin{bmatrix} \Psi(x, \lambda) \\ -\Phi(x) \end{bmatrix} + \begin{bmatrix} 0 \\ N_{\Theta}^{-1}(\lambda) \end{bmatrix}$$

and the solution map to the canonical perturbation of VS

$$S(v, w) := \left\{ (x, \lambda) \in \mathbb{R}^n \times \mathbb{R}^m \mid (v, w) \in G(x, \lambda) \right\}, \quad (v, w) \in \mathbb{R}^n \times \mathbb{R}^m$$

DEFINITION Given a solution $(\bar{x}, \bar{\lambda})$ to (VS), we say the **semi-isolated calmness** holds for S if there exist $\varepsilon > 0$, $\ell \geq 0$, and neighborhoods $V \times W$ of $(0, 0) \in \mathbb{R}^n \times \mathbb{R}^m$ such that

$$S(v, w) \cap \mathcal{B}_{\varepsilon}(\bar{x}, \bar{\lambda}) \subset \left[\{\bar{x}\} \times \Lambda(\bar{x}) \right] + \ell(\|v\| + \|w\|) \mathcal{B} \quad \text{for } (v, w) \in V \times W$$

CHARACTERIZATIONS OF NONCRITICAL MULTIPLIERS

THEOREM Let $(\bar{x}, \bar{\lambda})$ be a solution to the variational system (VS). Consider the properties

- (i) The Lagrange multiplier $\bar{\lambda} \in \Lambda(\bar{x})$ is **noncritical**
- (ii) There are numbers $\varepsilon > 0$, $\ell \geq 0$ and neighborhoods (V, W) of $(0, 0) \in \mathbb{R}^n \times \mathbb{R}^m$ such the **semi-isolated calmness** holds
- (iii) There are numbers $\varepsilon > 0$ and $\ell \geq 0$ with the **error bound**

$$\|x - \bar{x}\| + d(\lambda; \Lambda(\bar{x})) \leq \ell \left(\|\Psi(x, \lambda)\| + d(\Phi(x); N_{\Theta}^{-1}(\lambda)) \right), \quad (x, \lambda) \in \mathcal{B}_{\varepsilon}(\bar{x}, \bar{\lambda})$$

Then we have the assertions

- (a) Implications (iii) \iff (ii) \implies (i) always fulfill
- (b) If Θ is **\mathcal{C}^2 -cone reducible** at $\bar{z} = \Phi(\bar{x})$ to a closed convex cone C , if the set

$$K_{\Theta}(\bar{z}, \bar{\lambda})^* - \left[K_{\Theta}(\bar{z}, \bar{\lambda})^* \cap \ker \nabla \Phi(\bar{x})^* \right]$$

is **closed**, and if the Lagrange multiplier mapping

$$M_{\bar{x}}(v, w) := \left\{ \lambda \in \mathbb{R}^m \mid (v, w) \in G(\bar{x}, \lambda) \right\} \text{ for all } (v, w) \in \mathbb{R}^n \times \mathbb{R}^m$$

is **calm** at $((0, 0), \bar{\lambda})$, then the **converse** (i) \implies (ii) also holds

Note that the imposed **calmness** and **closedness** assumptions hold **automatically** if Θ is a **convex polyhedron** (by Hoffman's lemma). Otherwise, they are essential for noncriticality

SPECIAL CASE

THEOREM Let $(\bar{x}, \bar{\lambda})$ be a solution to the variational system (VS). Then the following are equivalent

- (i) The Lagrange multiplier $\bar{\lambda} \in \Lambda(\bar{x})$ is **noncritical**, $\Lambda(\bar{x}) = \{\bar{\lambda}\}$, and the Lagrange multiplier mapping $M_{\bar{x}}$ is **calm** at $((0, 0), \bar{\lambda})$
- (ii) The solution mapping S is **isolated calm** at $((0, 0), (\bar{x}, \bar{\lambda}))$

Here closedness assumption holds automatically since we can show that

$$K_{\Theta}(\bar{z}, \bar{\lambda})^* - \underbrace{\left[K_{\Theta}(\bar{z}, \bar{\lambda})^* \cap \ker \nabla \Phi(\bar{x})^* \right]}_{=\{0\}} = K_{\Theta}(\bar{z}, \bar{\lambda})^*$$

SECOND-ORDER CONDITIONS

DEFINITION Let $(\bar{x}, \bar{\lambda})$ be a solution to (VS) under the \mathcal{C}^2 -cone reducibility of Θ . The **the second-order condition** is

$$\langle \nabla_x \Psi(\bar{x}, \bar{\lambda}) \xi, \xi \rangle + \langle \nabla^2 \langle \bar{\mu}, h \rangle(\bar{z}) \nabla \Phi(\bar{x}) \xi, \nabla \Phi(\bar{x}) \xi \rangle > 0$$

for all $0 \neq \xi \in \mathbb{R}^n$ with $\nabla \Phi(\bar{x}) \xi \in K_\Theta(\bar{z}, \bar{\lambda})$

In the case of constrained optimization (CO) this condition reduces to the **second-order sufficient condition**

$$\langle \nabla_{xx}^2 L(\bar{x}, \bar{\lambda}) u, u \rangle + \langle \nabla^2 \langle \bar{\mu}, h \rangle(\bar{z}) \nabla \Phi(\bar{x}) u, \nabla \Phi(\bar{x}) u \rangle > 0$$

for all $0 \neq u \in \mathbb{R}^n$ with $\nabla \Phi(\bar{x}) u \in K_\Theta(\bar{z}, \bar{\lambda})$

which can be equivalent described via the **sigma term**. The latter is a bit **stronger** than the **classical second-order sufficient condition** for (CO) corresponding to

$$\sup_{\bar{\lambda} \in \Lambda_c(\bar{x})} \left\{ \langle \nabla_{xx}^2 L(\bar{x}, \bar{\lambda}) u, u \rangle \dots \right\}$$

while it ensures the **multiplier noncriticality**

NONCRITICALITY UNDER SECOND-ORDER CONDITION

THEOREM Let $(\bar{x}, \bar{\lambda})$ be a solution to (VS), let Θ be \mathcal{C}^2 -cone reducible at $\bar{z} = \Phi(\bar{x})$ to a closed convex cone C , and let the multiplier mapping $M_{\bar{x}}$ be calm at $((0, 0), \bar{\lambda})$. If the **second-order condition holds**, then the solution map S from is **semi-isolatedly calm** at $((0, 0), (\bar{x}, \bar{\lambda}))$, and hence $\bar{\lambda}$ is a **noncritical multiplier** corresponding to \bar{x}

NONCRITICALITY UNDER STRICT COMPLEMENTARITY

Strict complementarity holds at \bar{x} on (VS) if there exists there $\lambda \in \Lambda(\bar{x})$ such that $\lambda \in \text{ri } N_{\Theta}(\Phi(\bar{x}))$ (Bonnans-Shapiro, 2000)

THEOREM Let \bar{x} be a stationary point for (VS), let Θ be \mathcal{C}^2 -cone reducible at $\bar{z} = \Phi(\bar{x})$ to a closed convex cone C , and let the strict complementarity condition hold at \bar{x} . Then a Lagrange multiplier $\bar{\lambda} \in \Lambda(\bar{x})$ is noncritical if and only if either semi-isolated calmness or error bound condition is satisfied

Here we do not impose the calmness and closedness assumptions of the general characterization theorem for noncriticality

SEQUENTIAL QUADRATIC PROGRAMMING METHOD

Consider the constrained optimization problem

$$\text{minimize } \varphi(x) \text{ subject to } \Phi(x) \in \Theta$$

ALGORITHM (basic SQP method) Choose any $(x_k, \lambda_k) \in \mathbb{R}^n \times \mathbb{R}^m$ and set $k = 0$

- If (x_k, λ_k) satisfies the KKT system, then stop
- Compute (x_{k+1}, λ_{k+1}) as a solution to the KKT system (with $H_k = \nabla^2 L(x_k, \lambda_k)$)

$$\begin{aligned} \min & \varphi(x_k) + \langle \nabla \varphi(x_k), x - x_k \rangle + \frac{1}{2} \langle H(x_k)(x - x_k), x - x_k \rangle \\ \text{subject to } & \Phi(x_k) + \nabla \Phi(x_k)(x - x_k) \in \Theta \end{aligned}$$

- Increase k by 1 and then go back to Step 1

SUPERLINEAR CONVERGENCE OF SQP METHOD

THEOREM Assume that

- \bar{x} is a local minimizer and $\Lambda(\bar{x}) = \{\bar{\lambda}\}$
- $\bar{\lambda}$ is noncritical
- The multiplier mapping $M_{\bar{x}}$ is calm at $((0, 0), \bar{\lambda})$

Then for any starting point (x_0, λ_0) sufficiently close to $(\bar{x}, \bar{\lambda})$, the SQP method converges to $(\bar{x}, \bar{\lambda})$ and the rate of convergence is superlinear

FULL STABILITY OF LOCAL MINIMIZERS

Following [LevPolRoc00], consider the two-parameter perturbation (2P) of (CO) defined by

$$\text{minimize } \varphi_0(x) + \theta(\Phi(x) + p_2) - \langle p_1, x \rangle, \quad x \in \mathbb{R}^n$$

For fixed $\gamma > 0$ and parameters $(p_1, p_2) \in \mathbb{R}^n \times \mathbb{R}^l$ define

$$m_\gamma(p_1, p_2) = \inf_{\|x - \bar{x}\| \leq \gamma} \left\{ \varphi_0(x) + \theta(\Phi(x) + p_2) - \langle p_1, x \rangle \right\}$$

$$M_\gamma(p_1, p_2) = \operatorname{argmin} \left\{ \varphi_0(x) + \theta(\Phi(x) + p_2) - \langle p_1, x \rangle \mid \|x - \bar{x}\| \leq \gamma \right\}$$

Then \bar{x} is a **fully stable** locally optimal solution to (2P) if the mapping $(p_1, p_2) \mapsto M_\gamma(p_1, p_2)$ is **locally single-valued and Lipschitzian** with $M_\gamma(0, 0) = \{\bar{x}\}$ and the function $(p_1, p_2) \mapsto m_\gamma(p_1, p_2)$ is locally Lipschitzian around $(0, 0)$ for some $\gamma > 0$

EXCLUDING CRITICAL MULTIPLIERS

THEOREM [M19] Let \bar{x} be a **fully stable** local optimal solution to (CO) when **either** $\theta \in CPWL$ **or** $\theta = \delta_\Gamma$ where Γ is C^2 -**reducible** Then the Lagrange multiplier set $\Lambda_{\text{com}}(\bar{x})$ **in does not include any critical multipliers**

By now we have **complete second-order characterizations** of full stability for various classes of optimization and optimal control problems as well as variational systems; see, e.g., [MorNghiaRoc16] with the references therein. This allows us to efficiently determine settings where critical multipliers **do not appear** and thus **slow convergence is eliminated**

Tilt stability ($p_2 = 0$) may not rule out critical multipliers, but it does under certain **nondegeneracy conditions** as well as in some other cases

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